

# Theory Evolution in Physics

Alan Bundy

(Joint work with Jos Lehmann and Michael Chan)

School of Informatics,  
University of Edinburgh

University of St Andrews, 27<sup>th</sup> November 2013



# Outline

- 1 Representational Change in Physics
- 2 Theory Repair Plans
- 3 Where's My Stuff?
- 4 Inconstancy
- 5 Unite
- 6 The Architecture of GALILEO
- 7 Conclusion



# Representational Change in Scientific Revolutions

**Concepts Splitting:** heat becomes energy and temperature.

*one function becomes two.*

**Concepts Merging:** morning star and evening star become Venus.

*two constants become one.*

**Dependencies Increase:** gravitational 'constant' depends on accel.

*function gains an argument.*

**Dependencies Decrease:** gravitational accel independent of mass.

*function loses an argument.*



# Evolution in 'Normal' Science

- “Essentially, all models are wrong, but some are useful” (Box & Draper 1987)  
“But, it’s turtles all the way down.” (old lady quoted by Hawking 1988)
- Deciding what to include and what to neglect:  
*frictionless pulleys, inextensible strings, inelastic collisions.*
- Experimental evidence may cause initial modelling decision to be revoked.



# Issues in Theory Evolution

- Need theory development history for evaluation.
  - Lots of well documented case studies in physics domain.
- Search arises from diagnosis/repair choices as well as inference.
  - *Proof plans* previously used to control search.
  - Adapted proof plans to *theory repair plans*.
- Representational refinements incompletely defined.
  - Splitting a function: which new function replaces each occurrence of an old one?
  - Adding an argument: what values should its occurrences take?
  - Theory repair plans complete refinement definitions.
  - Multiple small theories facilitate targeted repairs.



# Theory Repair Plans

Aggregate atomic operations into theory repair plans.

- Atomic operations: split/merge functions, add/remove arguments, etc.
- Trigger formula signals applicability and instantiates plan.
- Repairs change language as well as beliefs.
- Multiple theories used in both trigger and repair.



# Example Theory Repair Plans

- The *Where's My Stuff?* theory repair plan.
  - Triggered by conflict between predicted and observed values of *stuff*.
  - Splits old *stuff* into visible, invisible and total *stuff*.
- The *Inconstancy* theory repair plan.
  - Triggered by conflict between predicted independence and observed dependence.
  - Adds this dependency as new argument to *stuff*.
- The *Unite* theory repair plan.
  - Triggered because two objects are the same on defining property.
  - Equates these two objects.



# Why Higher-Order Logic?

- Many concepts in Physics are naturally higher-order,
  - e.g. orbit of planet:  $\lambda t. Posn(Uranus, t)$ .
  - differential and integral calculus:  $Diff(Sin) = Cos$ .
  - So, higher-order needed at object-level.
- Polymorphic nature of theory repair plans.
  - e.g. *stuff*,  $=$ ,  $<$   $-$ .
  - Need to quantify over types.
  - So, higher-order needed at meta-level too.





# The GALILEO System

- Implementing TRPs in the GALILEO system using Isabelle and its locales.
  - GALILEO:** *Guided Analyses of Logical Inconsistencies Leads to Evolved Theories.*
  - Isabelle:** Generic proof assistant. Higher-order theorem prover.
  - Locales:** Isabelle's mechanism for context handling.
- Successfully evaluated on several TRPs.



# The 'Where's My Stuff?' Theory Repair Plan

## Trigger

$$O_t \vdash \mathit{stuff}(\vec{s}) = v_1, \quad O_s \vdash \mathit{stuff}(\vec{s}) = v_2, \quad O_t \vdash v_1 > v_2$$

## Split stuff

$$\forall \vec{s} : \vec{\tau}. \mathit{stuff}_{\mathit{invis}}(\vec{s}) ::= \mathit{stuff}(\vec{s}) - \mathit{stuff}_{\mathit{vis}}(\vec{s})$$

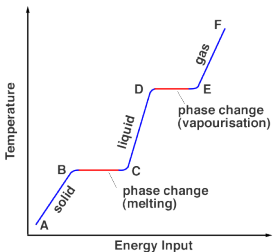
## Create new axioms

$$\mathit{Ax}(\nu(O_t)) ::= \{ \forall \vec{s} : \vec{\tau}. \mathit{stuff}_{\mathit{invis}}(\vec{s}) ::= \mathit{stuff}(\vec{s}) - \mathit{stuff}_{\mathit{vis}}(\vec{s}) \} \\ \cup \mathit{Ax}(O_t)$$

$$\mathit{Ax}(\nu(O_s)) ::= \{ \phi \{ \mathit{stuff} / \mathit{stuff}_{\mathit{vis}} \} \mid \phi \in \mathit{Ax}(O_s) \}$$



# The Latent-Heat Paradox



- Before Joseph Black's investigations, heat and temperature conflated.
- Leads to paradox when heat is reduced but temperature is constant!
- Latent heat: the (hidden) heat energy involved in the phase change of a substance.

# Application to the Latent-Heat Paradox

## Example

### Original theories:

$$O_t \vdash \text{Heat}(H_2O, \text{Melt}) = \text{Heat}(H_2O, \text{Melt})$$

$$O_s \vdash \text{Heat}(H_2O, \text{Melt}) = 0$$

$$O_t \vdash \text{Heat}(H_2O, \text{Melt}) > 0$$

---

**Substitution:**  $\{\text{Heat}/\text{stuff}, \langle H_2O, \text{Melt} \rangle / \vec{s}, \text{Heat}(H_2O, \text{Melt}) / v_1, 0 / v_2\}$

---

### Splitting stuff:

$\forall o : \text{obj}, e : \text{event}. \text{LHF}(o, e) ::= \text{Heat}(o, e) - \text{Temp}(o, e)$

---

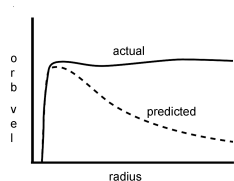
### Repaired theories:

$$\nu(O_t) \vdash \text{Heat}(H_2O, \text{Melt}) > 0$$

$$\nu(O_s) \vdash \text{Temp}(H_2O, \text{Melt}) = 0$$



# Dark Matter



- Newtonian mechanics can predict relationship between orbital velocity and radius of stars.
- But actual relationship is different!
- Dark matter: some invisible matter surrounding the visible matter in a halo.



# Application to the Discovery of Dark Matter

## Example

Original theories:

$$O_t \vdash \lambda s \in \text{Spiral}. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle = \text{Graph}_p$$

$$O_s \vdash \lambda s \in \text{Spiral}. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle = \text{Graph}_a$$

$$O_t \vdash \text{Graph}_p < \text{Graph}_a$$

---

Substitution:  $\{ \lambda s \in g. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle / \text{stuff}, \langle \text{Spiral} \rangle / \bar{s}, \text{Graph}_p / v_1, \text{Graph}_a / v_2 \}$

---

Splitting stuff:

$$\lambda s \in \text{Spiral}_{\text{invis}}. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle$$

$$::= \lambda s \in \text{Spiral}. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle$$

$$- \lambda s \in \text{Spiral}_{\text{vis}}. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle$$


---

Repaired theories:

$$\nu(O_t) \vdash \lambda s \in \text{Spiral}_{\text{vis}}. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle = \text{Graph}_p$$

$$\nu(O_s) \vdash \lambda s \in \text{Spiral}. \langle \text{Rad}(s), \text{Orb\_Vel}(s) \rangle = \text{Graph}_a$$



# The Inconstancy Theory Repair Plan

## Trigger

$$\begin{array}{l}
 O_t \vdash \text{stuff}(\vec{x}) ::= c(\vec{x}) \\
 O_s(V(\vec{s}, \vec{b}_1) = v_1) \vdash \text{stuff}(\vec{s}) = c_1(\vec{s}) \\
 \vdots \\
 O_s(V(\vec{s}, \vec{b}_n) = v_n) \vdash \text{stuff}(\vec{s}) = c_n(\vec{s}) \\
 \exists i \neq j. O_t \vdash c_i(\vec{s}) \neq c_j(\vec{s})
 \end{array}$$

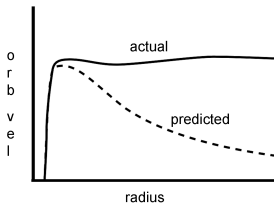
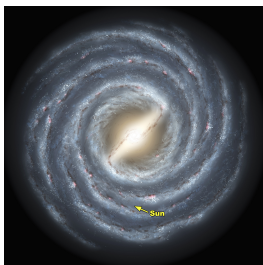
## Add variad

$$\nu(\text{stuff}) ::= \lambda \vec{y}, \vec{x}. F(c(\vec{x}), V(\vec{x}, \vec{y}))$$

## Create new axioms

$$\begin{array}{l}
 \text{Ax}(\nu(O_t)) ::= \{ \phi \{ \text{stuff} / \nu(\text{stuff})(\vec{y}) \} \mid \phi \in \text{Ax}(O_t) \\
 \quad \setminus \{ \text{stuff}(\vec{x}) ::= c(\vec{x}) \} \} \\
 \quad \cup \{ \nu(\text{stuff}) ::= \lambda \vec{y}, \vec{x}. F(c(\vec{x}), V(\vec{x}, \vec{y})) \} \\
 \text{Ax}(\nu(O_s(V(\vec{s}, \vec{b}_i) = v_i))) ::= \{ \phi \{ \text{stuff} / \nu(\text{stuff})(\vec{b}_i) \} \mid \phi \in \text{Ax}(O_s(V(\vec{s}, \vec{b}_i) = v_i)) \}
 \end{array}$$

# MOdified Newtonian Dynamics (MOND)



- Newtonian theory of gravity predicted that objects further out will have lower velocities.
- The observed velocities of those objects are almost constant!
- MOND - The gravitational force ( $F = \frac{G \times M \times m}{r^2}$ ) is different at low accelerations.





# Application to MOND

## Example

Original theories:

$$\begin{aligned}
 O_t &\vdash G ::= 6.67 \times 10^{-11} \\
 O_s(\text{Acc}(S_1) = A_1) &\vdash G = M2OV^{-1}(OV(S_1), \text{Mass}(S_1), \\
 &\quad \lambda s \in \text{Spiral} \setminus \{S_1\}. (\text{Posn}(s), \text{Mass}(s))) (= G_1) \\
 &\quad \vdots \\
 &\quad \vdots \\
 O_s(\text{Acc}(S_n) = A_n) &\vdash G = M2OV^{-1}(OV(S_n), \text{Mass}(S_n), \\
 &\quad \lambda s \in \text{Spiral} \setminus \{S_n\}. (\text{Posn}(s), \text{Mass}(s))) (= G_n) \\
 \exists i \neq j. O_t &\vdash G_i \neq G_j
 \end{aligned}$$

---

**Substitution:**  $\{G/\text{stuff}, \langle \rangle/\vec{s}, \langle \rangle/\vec{x}, 6.67 \times 10^{-11}/c, \text{Acc}/V, \langle S_i \rangle/\vec{b}_i, G_1/c_1, G_n/c_n\}$

---

**New Definition:**  $\nu(G) ::= \lambda s. F(6.67 \times 10^{-11}, \text{Acc}(s))$

---

Repaired theories:

$$\begin{aligned}
 \nu(O_t) &\vdash \nu(G) ::= \lambda s. F(6.67 \times 10^{-11}, \text{Acc}(s)) \\
 \nu(O_s(\text{Acc}(S_1) = A_1)) &\vdash \nu(G)(S_1) = M2OV^{-1}(OV(S_1), \text{Mass}(S_1), \\
 &\quad \lambda s \in \text{Spiral} \setminus \{S_1\}. (\text{Posn}(s), \text{Mass}(s))) (= G_1) \\
 &\quad \vdots \\
 &\quad \vdots \\
 \nu(O_s(\text{Acc}(S_n) = A_n)) &\vdash \nu(G)(S_n) = M2OV^{-1}(OV(S_n), \text{Mass}(S_n), \\
 &\quad \lambda s \in \text{Spiral} \setminus \{S_n\}. (\text{Posn}(s), \text{Mass}(s))) (= G_n)
 \end{aligned}$$

# The Unite Theory Repair Plan

Trigger:

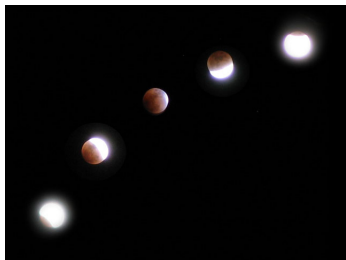
$$\begin{aligned}
 O_t &\not\vdash \textit{stuff}_1 = \textit{stuff}_2, \\
 O_t &\vdash \textit{stuff}_1:\tau \wedge \textit{stuff}_2:\tau \wedge \textit{DefProp}(dp, \tau), \\
 O_s &\vdash dp(\textit{stuff}_1) = dp(\textit{stuff}_2).
 \end{aligned}$$

Repair:

$$Ax(\nu(O_t)) ::= \{\textit{stuff}_1 = \textit{stuff}_2\} \cup Ax(O_t)$$



# The Earth as a Sphere



- Shadow of Earth on Moon always circular.
  - Seen during lunar eclipse.
- Pythagoras realised family of projections was *defining property* of volumes.
- Only sphere has only circular projections.
- Therefore, Earth is spherical.

# Application to the Earth as a Sphere

Trigger:

$$O_t \not\vdash \text{Shape}(\text{Earth}) = \text{Shape}(\text{Ball})$$

$$O_t \vdash \text{Shape}(\text{Earth}) : \text{vol} \wedge \text{Shape}(\text{Ball}) : \text{vol} \\ \wedge \text{DefProp}(\lambda v, t. \text{project}(v, \text{Sun}, \text{Moon}, t), \text{vol})$$

$$O_s \vdash \lambda t. \text{project}(\text{Shape}(\text{Earth}), \text{Sun}, \text{Moon}, t) \\ = \lambda t. \text{project}(\text{Shape}(\text{Ball}), \text{Sun}, \text{Moon}, t)$$

Repair:

$$\text{Ax}(\nu(O_t)) ::= \{\text{Shape}(\text{Earth}) = \text{Shape}(\text{Ball})\} \cup \text{Ax}(O_t)$$



# Conservative Extensions and Minimal Repairs

- Want repairs to be minimal.
- Adapt *conservative extension*.

$$\phi \in \text{Lang}(O) \implies (\nu(O) \vdash \nu(\phi) \iff O \vdash \phi)$$

- In WMS, both  $\nu(O_t)$  and  $\nu(O_s)$  are conservative in this sense.

$$\begin{aligned} \text{Ax}(\nu(O_t)) ::= & \{ \forall \vec{s} : \vec{\tau}. \text{stuff}_{\text{invis}}(\vec{s}) ::= \text{stuff}(\vec{s}) - \text{stuff}_{\text{vis}}(\vec{s}) \} \\ & \cup \text{Ax}(O_t) \end{aligned}$$

$$\text{Ax}(\nu(O_s)) ::= \{ \phi \{ \text{stuff} / \text{stuff}_{\text{vis}} \} \mid \phi \in \text{Ax}(O_s) \}$$

- The combined theories are *not* conservative.
- Situation more complicated for Unite and Inconstancy.



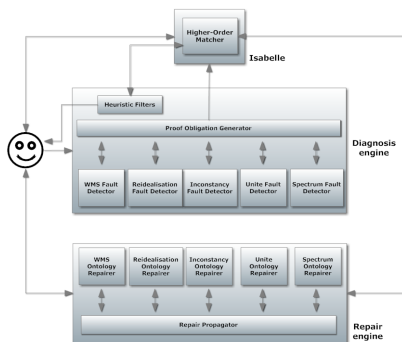
# Multiple Small Theories in Repair Plans

Why have separate theoretical and sensory theories?

- Enables control over contradiction.
- Focuses effect of repair operations.
- Allows use of conservative extension to show minimality.
- Could allocate different degrees of belief to each theory.

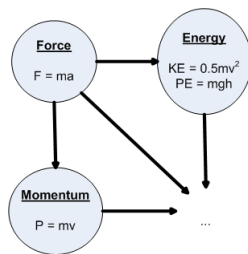


# Overview of Architecture



- The reasoning engine tries to prove the repair trigger.
- If this succeeds, then the transformation rules are applied to the development graph.

# Development Graphs in Isabelle Locales



- Based on Institution Theory:
  - Nodes are theories; arrows are morphisms.
- Represent multiple theories in development graph
- Later theories can build on earlier ones.
- Add/remove theories automatically during evolution.



# Inferring Trigger Formulae in Isabelle

- GALILEO coordinates Isabelle's proof of trigger formula.
- Isabelle's locales mechanism used to organise multiple theories.
- Proofs interactive.
- *stuff*, *f*, etc. instantiated during proof.
- Repairs then suggested by theory repair plan.



# Search Control Heuristics

- Vast number of potential instantiations of  $f$  and  $stuff$ .
- Heuristically prune instantiations with no Physics meaning, e.g., for  $stuff$ , filter out instantiations:
  - containing the identity function:  $\dots \lambda x. x \dots$ ;
  - containing unbound function variables:  $\dots x(\dots) \dots$ ;
  - not containing a constant, e.g.,  $x(y, z)$ ;
  - with a  $\lambda$  abstracted variable as head:  $\lambda x. x(\dots)$ .

Similar for  $f$ .

- Usually remaining instantiations suggest a small number of physical meaningful alternative repairs.



# Conclusion

- Theory evolution is a key technology for adaptive, autonomous agents.
- Physics is good development domain because of historical record.
- Higher-order logic needed at object- and meta-levels.
- Repair plans address problems of search and ambiguity.
- Developed and tested several repair plans.
- Implemented GALILEO system using Isabelle and its locales.

